

Finite Volume Discretization Techniques of Differential Operators

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The scalar transport equation

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We use the **finite-volume method** (FVM) to solve the flow governing equations. The **integral form** of the scalar transport equation (STE) must be discretized and solved:

$$\int_{V} \frac{\partial \phi}{\partial t} \, dV + \int_{A} (u_{j}\phi) n_{j} \, dA = \int_{A} D \frac{\partial \phi}{\partial x_{j}} n_{j} \, dA + \int_{V} (S_{\phi}) \, dV$$

Discretization steps:

- Numerical integration
- Time-advancement schemes
- Differentiation schemes
- Interpolation schemes



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The important properties of a numerical schemes are:

- **Convergence/accuracy**: the numerical solution should converge to the exact solution of the PDE as the mesh size tends to zero
- Conservation: underlying conservation laws should be respected at the discrete level
- **Boundedness**: quantities like density, temperature and concentration should remain non-negative and free of spurious wiggles/spikes

And what about the spectral-resolution?

The discrete transport equation

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If we **integrate in time** the semi-discrete transport equation and we apply the unconditionally stable backward Euler scheme we get:

$$(\phi^{n+1} - \phi^n)\Delta V + \sum_f (u_j^n \phi^{n+1})_f A_{fj} = \sum_f D_f \frac{\partial \phi^{n+1}}{\partial x_j} \bigg|_f A_{fj} + S_{\phi}^{n+1} \Delta V$$

Note that the **midpoint rule** is **second-order accurate** only if variables are evaluated at the **cell/face centroid**.



Discretization of differential operators

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$$(\phi^{n+1} - \phi^n)\Delta V + \sum_f (u_j^n \phi^{n+1})_f A_{fj} = \sum_f D_f \frac{\partial \phi^{n+1}}{\partial x_j} \bigg|_f A_{fj} + S_{\phi}^{n+1} \Delta V$$

We need to define the discretization method for the following operators:

- Cell-centered gradient
- Diffusion operator
- Convection operator



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The computation of **cell-centered gradients** is widely used in finite-volume schemes for **convection interpolation** and **diffusion discretization**.

On a uniform, one-dimensional stencil a **second-order accurate** formula based on **Taylor expansions** is the following:

Cell gradient computation II

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In the framework of **unstructured finite-volume schemes**, cell-centered gradients can be estimated via the **Gauss-Green theorem**:

$$\int_{V} \frac{\partial \phi}{\partial x_{j}} \, dV = \int_{A} \phi n_{j} \, dA$$

which, using the **midpoint rule** to evaluate the surface and volume integrals, gives:

$$\left. \frac{\partial \phi}{\partial x_j} \right|_c \approx \frac{1}{\Delta V} \sum_f \phi_f A_{fj}$$

where ϕ_f is the face-interpolated value.



Cell gradient computation III

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The face interpolated value as well can be estimated via Taylor expansions:

$$\phi_{0} = \phi_{f} - \frac{\partial \phi}{\partial s} \bigg|_{f} \Delta s_{0} + \frac{\partial^{2} \phi}{\partial s^{2}} \frac{\Delta s_{0}^{2}}{2} + \mathcal{O}(\Delta s_{0}^{3})$$
$$\phi_{1} = \phi_{f} + \frac{\partial \phi}{\partial s} \bigg|_{f} \Delta s_{1} + \frac{\partial^{2} \phi}{\partial s^{2}} \frac{\Delta s_{1}^{2}}{2} + \mathcal{O}(\Delta s_{1}^{3})$$

The **midPoint scheme** provides a simple **second-order** formula on **regular grids** ($\Delta s_0 = \Delta s_1$):

$$\phi_f^{MP} = \frac{\phi_1 + \phi_0}{2} + \mathcal{O}(\Delta s^2)$$



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In complex geometries the computational grid usually deviates from regular elements and **quality parameters** are thus introduced.

Mesh quality:

- Aspect ratio ($\Delta s_1/\Delta s_0$)
- Non-orthogonality (β)
- skewness (d)



Grid aspect ratio

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Mid-point rule:

$$\phi_f^{\mathcal{M}} = \frac{\phi_1 + \phi_0}{2} + \mathcal{O}(\Delta s^2)$$

Linear interpolation:

$$\phi_f^L = \phi_0 \lambda_0 + \phi_1 (1 - \lambda_0) + \mathcal{O}(\Delta s^2)$$
$$\lambda_0 = \frac{\Delta s_0}{\Delta s}, \quad \Delta s = \Delta s_0 + \Delta s_1$$
$$O_{\Delta s_0} = \Phi_{\Delta s_1} O_{\Delta s_1} O_{\Delta s_1}$$

Grid skewness

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Mid-point rule:

$$\phi_f^M = \frac{\phi_1 + \phi_0}{2} + \mathcal{O}(\Delta s^2)$$

Skew-corrected intepolation:

$$\phi_{m}^{L} = \phi_{0}\lambda_{0} + \phi_{1}\lambda_{1}, \quad \lambda_{1} = 1 - \lambda_{0}$$

$$(\nabla\phi)_{m}^{L} = (\nabla\phi)_{0}\lambda_{0} + (\nabla\phi)_{1}\lambda_{1}$$

$$\phi_{f}^{SC} = \phi_{m} + (\nabla\phi)_{m} \cdot d$$

Diffusion discretization I

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The discretization of the **diffusive flux** in the STE requires to evaluate the **scalar gradient** at the **face centroid**:

$$\int_{A} D \frac{\partial \phi}{\partial x_j} n_j \approx \sum_{f} D \frac{\partial \phi}{\partial x_j} \Big|_{f} A_{fj}$$

On regular grids, the face gradient can be evaluated via the central scheme:



Diffusion discretization II

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On **irregular** meshes, a **correction** for the **grid non-orthogonality**, when severe, might be needed to improve the accuracy of the numerical solution:

$$\frac{\partial \phi}{\partial x_j} \Big|_f A_{fj} = |\Delta| \frac{\phi_1 - \phi_0}{\Delta s} + k \cdot (\nabla \phi)_f$$

where

$$(\nabla\phi)_f = (\nabla\phi)_0\lambda_0 + (\nabla\phi)_1\lambda_1$$

is used to build up the correction term.



Convection interpolation operators I

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The discretization of the **convection operator** requires to evaluate the field at the **face centroid**.

A second-order accurate **central interpolation** on irregular meshes can be obtained using a **two-sided linear expansion** [1]:

$$\phi_f = \frac{1}{2}(\phi_0 + \phi_1) + \frac{1}{2} \left[\frac{\partial \phi}{\partial x_i} \Big|_0 R_{0i} + \frac{\partial \phi}{\partial x_i} \Big|_1 R_{1i} \right] + \mathcal{O}(\Delta s^2)$$

Alternatively, using a one-sided linear expansion, upwind schemes are obtained:

$$\phi_f = \phi_u + \frac{\partial \phi}{\partial x_i} \Big|_{u} R_{ui} + \mathcal{O}(\Delta s^2)$$

[1] P. Batten, C. Lambert, D.M. Causon, Positively conservative high-resolution convection schemes for unstructured elements, Int. J. Numer. Methods Eng. 39 (1996) 1821.

Convection interpolation operators II

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Several convection interpolation schemes have been proposed in the context of the FV framework. We report here the **low-order** and **high-order** upwind and central interpolation schemes:

$$\begin{split} & \textbf{Upwind (FOU)}: \quad \phi_f = \phi_u + \mathcal{O}(\Delta s) \\ & \textbf{linearUpwind (SOU)}: \quad \phi_f = \phi_u + \frac{\partial \phi}{\partial x_i} \Big|_u R_{ui} + \mathcal{O}(\Delta s^2) \\ & \textbf{midPoint (LOCD)}: \quad \phi_f = \frac{1}{2}(\phi_0 + \phi_1) + \mathcal{O}(\Delta s^2) \\ & \textbf{reconCentral (HOCD)}: \quad \phi_f = \frac{1}{2}(\phi_0 + \phi_1) + \frac{1}{2} \Big[\frac{\partial \phi}{\partial x_i} \Big|_0 R_{0i} + \frac{\partial \phi}{\partial x_i} \Big|_1 R_{1i} \Big] + \mathcal{O}(\Delta s^2) \end{split}$$

Slope limiter

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In the framework of unstructured finite-volume schemes, **slope-limiting techniques** can be used to keep the **face-interpolation bounded**.

$$\phi_f = \phi_u + \min(\alpha_f) \frac{\partial \phi}{\partial x_j} \bigg|_u R_{uj}$$

For each cell, the **limiter** is given by:

$$\alpha_{f} = \begin{cases} \min(1, \frac{\phi_{\max} - \phi_{u}}{\phi_{f} - \phi_{u}}) & \text{if}(\phi_{f} - \phi_{u}) > 0\\ \min(1, \frac{\phi_{\min} - \phi_{u}}{\phi_{f} - \phi_{u}}) & \text{if}(\phi_{f} - \phi_{u}) < 0\\ 1 & \text{otherwise} \end{cases}$$

where ϕ_u is the cell-centroid value at the upwind side of the face.

OpenFOAM fvSchemes

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In OpenFOAM, the schemes for **gradient** (cell-centered) computation and **diffusion/convection** discretization are specified in the **fvSchemes** dictionary file located in the **system** folder:

```
gradSchemes
{
    default linear;
    grad(u) cellLimited Gauss skewCorrected midPoint 1;
}
divSchemes
{
    div(phi, u) Gauss linearUpwind grad(u);
}
laplacianSchemes
{
    Laplacian(D, u) Gauss linear corrected;
}
```

example I: computation of cell gradient SCtrain SUPERCOMPUTING KNOWLEDGE PARTNERSHIP

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Test function
$$T(x,y) = \frac{\partial T}{\partial x} = 2$$

ction:

$$T(x, y) = x^{2} + y^{2}$$
$$\frac{\partial T}{\partial x} = 2x, \quad \frac{\partial T}{\partial y} = 2y$$

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Sx - Gauss midPoint



Sx - Gauss skewCorrected linear

example I: computation of cell gradient Simone Bnà, Cineca



Sy - Gauss midPoint



Sy - Gauss skewCorrected linear

example II: Advection of a scalar profile I Sctrain Supercomputing KNOWLEDGE Simone Bnà, Cineca

The (pure) **advection** of a scalar profile in uniform flow can be used to investigate the **conservation and spectral properties** of CIOs.



Flow parameters:

$$\begin{split} \frac{\partial \phi}{\partial t} + U \frac{\partial \phi}{\partial x} &= 0 , U = 1 \\ \phi(x,0) &= \begin{cases} \cos^2(2\pi x) & \text{if} |x| \le 0.25 \\ 0 & \text{if} |x| > 0.25 \end{cases} \end{split}$$

example II: Advection of a scalar profile II Sctrain SUPERCOMPUTING Simone Bnà, Cineca



example II: Advection of a scalar profile II SCtrain SUPERCOMPUTING Simone Bnà, Cineca





Thank you for your attention!